

OpenKC - Feature #1

Add Support for Impedance Control Modes

2010-06-15 10:50 - Matthias Schöpfer

Status:	Closed	Start date:	2010-06-15
Priority:	Normal	Due date:	
Assignee:	Matthias Schöpfer	% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:		Spent time:	108.00 hours
Description			
Only Controller available under FRI is right now Position Control Add possibilities to change to Impedance Control modes			

History

#1 - 2010-07-06 12:26 - Matthias Schöpfer

- Status changed from New to In Progress
- Assignee set to Matthias Schöpfer
- % Done changed from 0 to 70

Waiting on message from Kuka if FRI_CMD_JNTPOS | FRI_CMD_CARTPOS is possible after all.

#2 - 2010-10-18 15:39 - Matthias Schöpfer

- Status changed from In Progress to Resolved
- % Done changed from 70 to 100

Finally, thanks to Michael Gerung from Kuka Roboter GmbH, we were able to resolve this issue!

#3 - 2011-06-10 10:48 - Matthias Schöpfer

- Status changed from Resolved to Closed